

A simple theory of cascades in networks

**Center for Institutional Studies Birthday Workshop
Higher School of Economics**

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Motivation

- Consumers care what products their friends and relatives use.
- Examples: innovation/technology adoption, social platform use, mobile phone contracts.
- Switching costs are often high: product adoption is **irreversible** (at least temporarily).
- Firms' **initial seeds** in the social network really matter for profit and market share.

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Previous work

- This work is mostly closely related to: Goyal and Kearns (2012); Bimpikis, Ozdaglar, and Yildiz (2014) (...and Hotelling, 1929)
- Quality and seeding: Fazeli and Jadbabaie (2012a,b,c); Fazeli, Ajorlou, and Jadbabaie (2014).
- Other papers where consumers can switch products many times: Bharathi, Kempe, and Salek (2007); Alon, Feldman, Procaccia, and Tennenholtz (2010); Apt and Markakis (2011); Simon and Apt (2012); Tzoumas, Amanatidis, and Markakis (2012); Borodin, Braverman, Lucier, and Oren (2013); Apt and Markakis (2014); Mei and Bullo (2014).

Outline of this talk

- We develop a tractable model of cascades in networks.
- We introduce a measure of node influence called **cascade centrality**.
- We study a competitive diffusion game on the network.
- We also characterize the expected number of adopters using cascade centrality in general graphs and find analytical expressions for many graphs.
- In a follow-up paper, we tackle network design questions: maximizing adoption and minimizing failures.

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Model

Preliminaries

- Simple, undirected graph $G(V, E)$.
- A *adoption threshold* for agent i is a random variable Θ_i drawn from a probability distribution with support $[0, 1]$.
- The associated multivariate probability distribution for all the agents in the graph is $f(\theta)$.
- Each agent is $i \in V$ assigned a threshold θ_i . Let's define the threshold profile of agents as $\theta := (\theta_i)_{i \in V}$. A **network** G_θ is a graph endowed with a threshold profile.

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Seeding

- Two firms: A selling product a and B selling product b . Products are perfectly substitutable.
- The state of agent i at time t is denoted $x_i(t) \in \{0, a, b\}$.
- Denote by $S_t^A(G_\theta)$ and $S_t^B(G_\theta)$ the sets of **new** adopters of products A and B in network G_θ at time t resp.
- At time $t = 0$, $x_i(0) = 0$ for all i , and each firm simultaneously chooses **one** agent $S_0^A, S_0^B \in V$ as a seed for their product. Overlap in seed sets resolved randomly.

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Linear threshold process dynamics

- Any agent who has not adopted any product by some period t , **decides to adopt one of the products** in time period $t + 1$ iff

$$\frac{\text{total friends who adopted } a + \text{total friends who adopted } b}{\text{total friends}} \geq \theta_i$$

i.e. Granovetter's linear threshold model.

- If the threshold is reached, the **probability of adopting product a** is

$$\frac{\# \text{ friends who adopted } a \text{ at } t}{\# \text{ friends who adopted } a \text{ at } t + \# \text{ friends who adopted } b \text{ at } t}$$

- Once an agent adopted product a , he remains in state a in all subsequent periods.
- This process converges to a random set: eventual adopters S^A of product a and S^B of product b .

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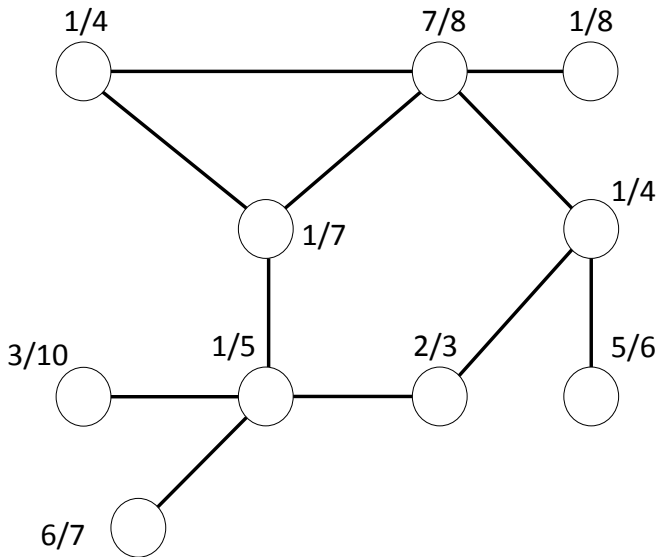
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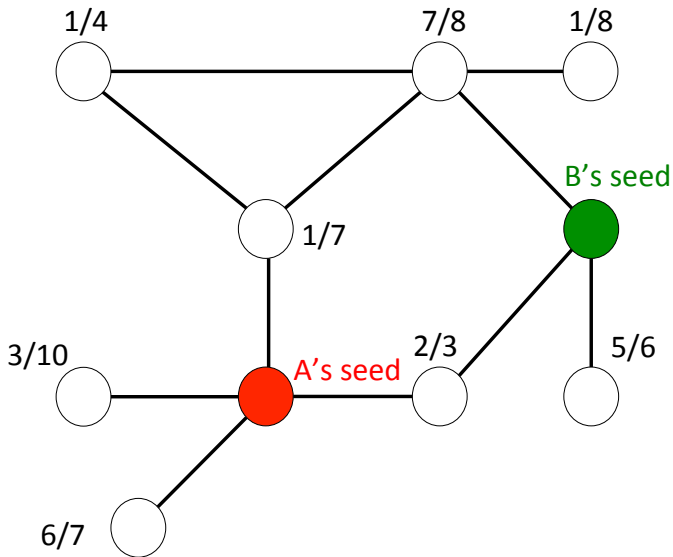
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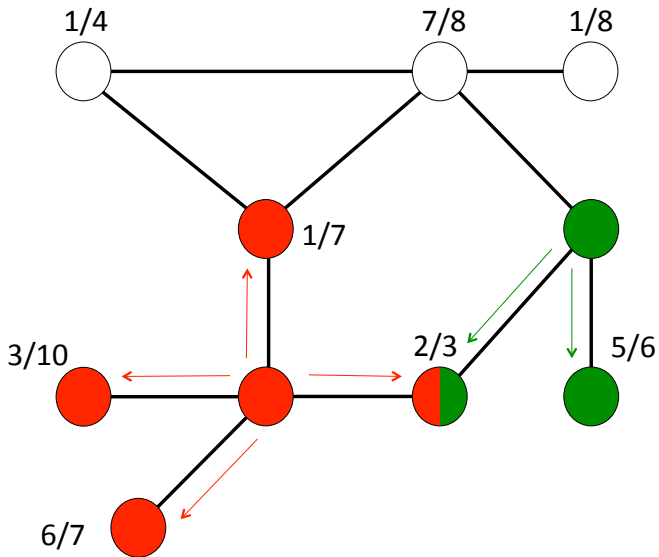
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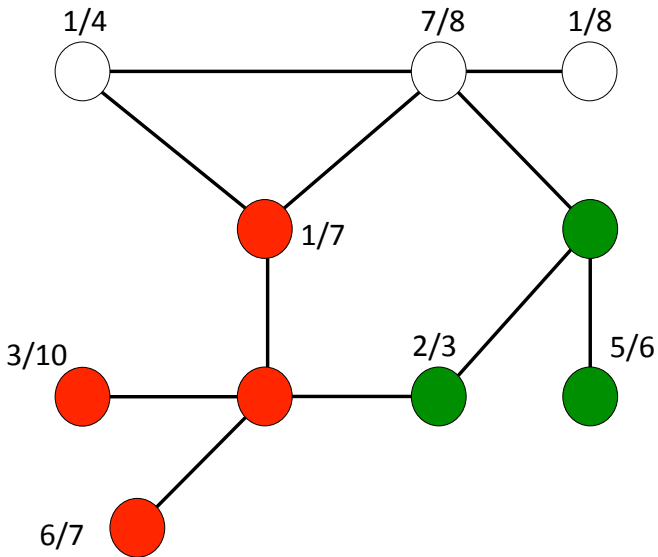
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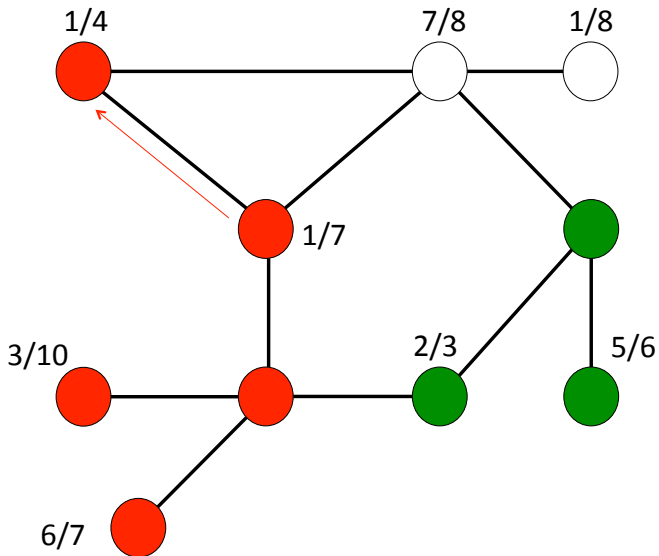
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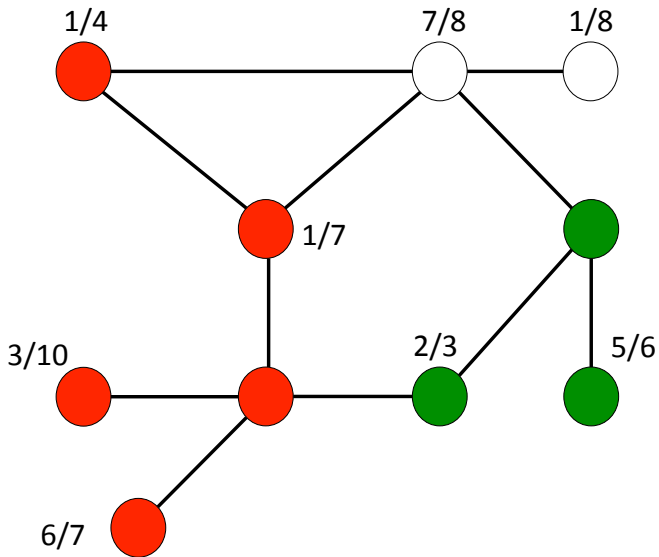












Expected number of adopters

- Fixing seeds S_0^A and S_0^B and a graph G , and re-run the process by drawing the agents' thresholds from $f(\theta)$ each time.
- Denoting the probability of any agent adopting product a is

$$\mathbb{P}_i^A(G, S_0^A, S_0^B) = \int_{\mathbb{R}^n} |S^A(G_\theta, S_0^A, S_0^B) \cap \{i\}| f(\theta) d\theta$$

- Expected number of adopters of product a is

$$\begin{aligned} \mathbb{E}[S^A(G, S_0^A, S_0^B)] &= \int_{\mathbb{R}^n} |S^A(G_\theta, S_0^A, S_0^B)| f(\theta) d\theta \\ &= \sum_{i=1}^n \mathbb{P}_i^A(G, S_0^A, S_0^B) \end{aligned}$$

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Consider what happens
when firm A is a monopolist

Uniform distribution

Assumption

For any G_θ and every $i \in V$, $\Theta_i \sim \mathcal{U}(0, 1)$ and independent.

It's the Laplacian prior for the firms. Moreover, we prove that

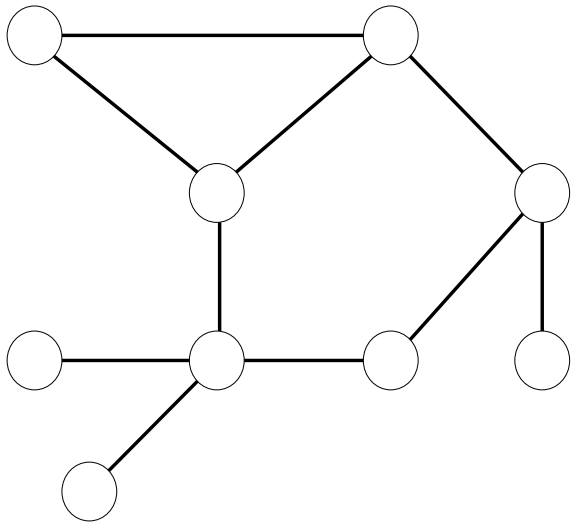
$$\mathbb{P}_i^A(G) = \sum_{j \in N_i(G)} \frac{\mathbb{P}_j^A(G | i \notin S^A)}{d_j}$$

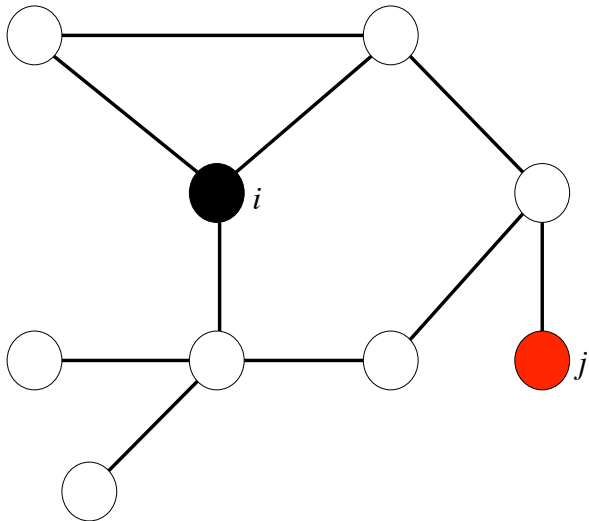
if and only if $\Theta_i \sim \mathcal{U}(0, 1)$.

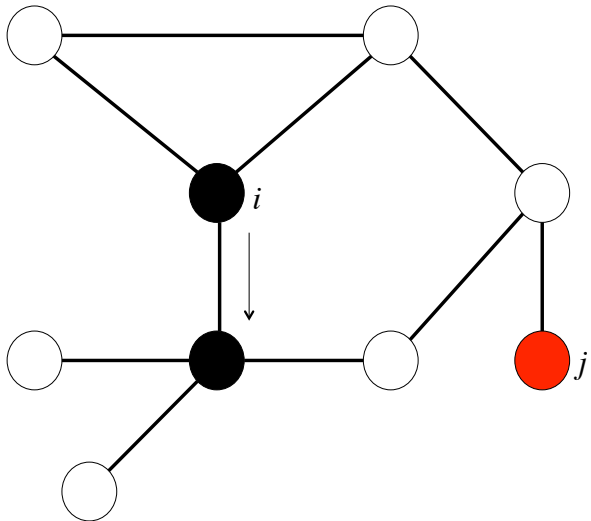
Paths

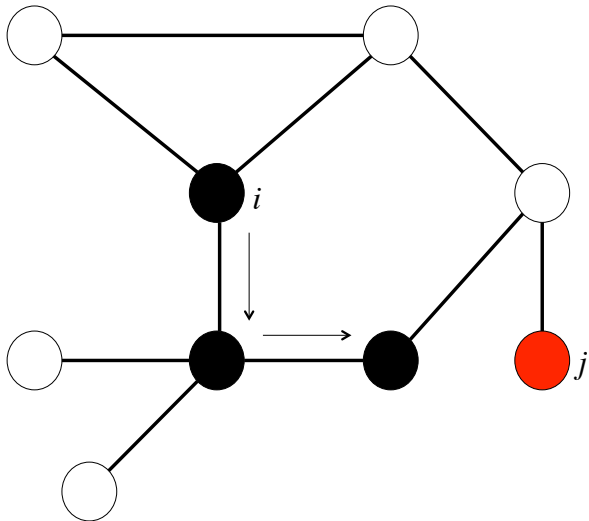
Definition

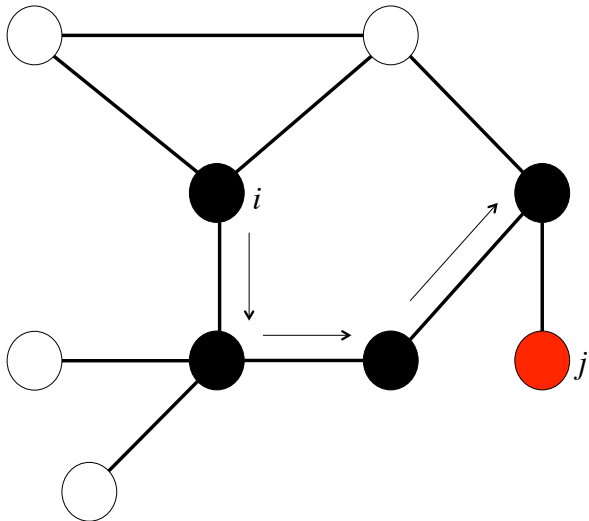
A sequence of nodes $P = (i_0, \dots, i_k)$ on a graph G is a path if $i_j \in N_{i_{j-1}}(G)$ for all $1 \leq j \leq k$ and each $i_j \in P$ is distinct.

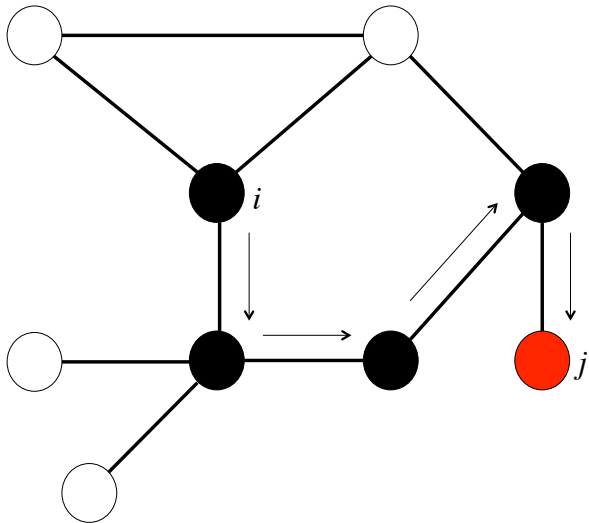


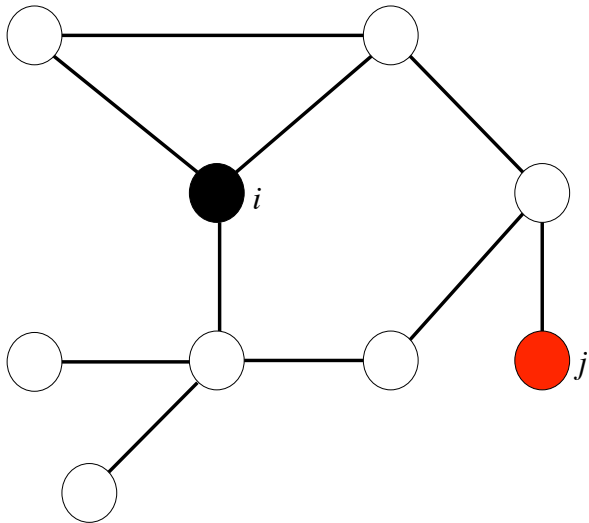


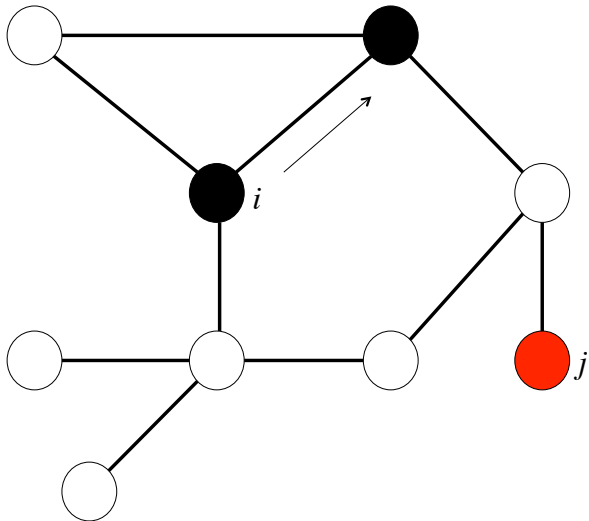


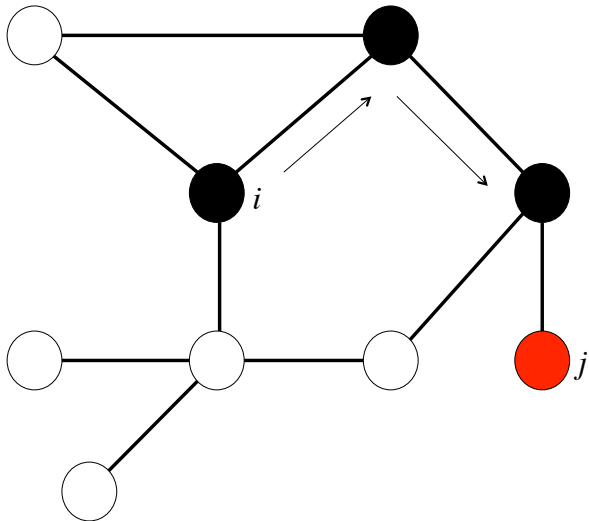


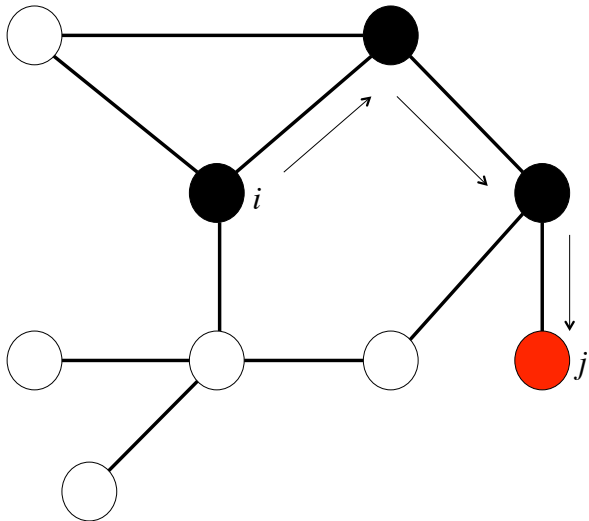


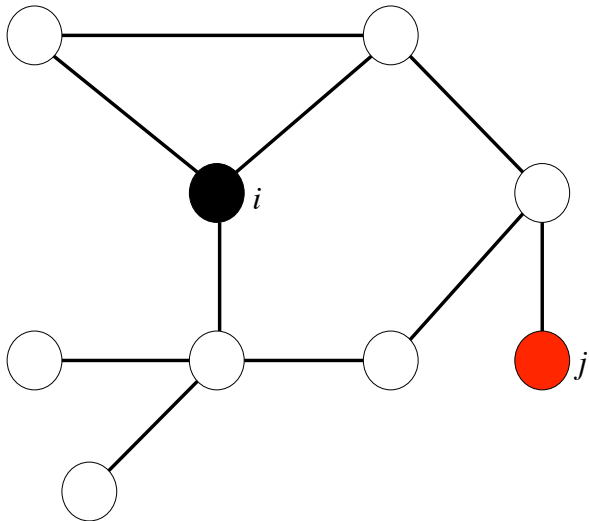


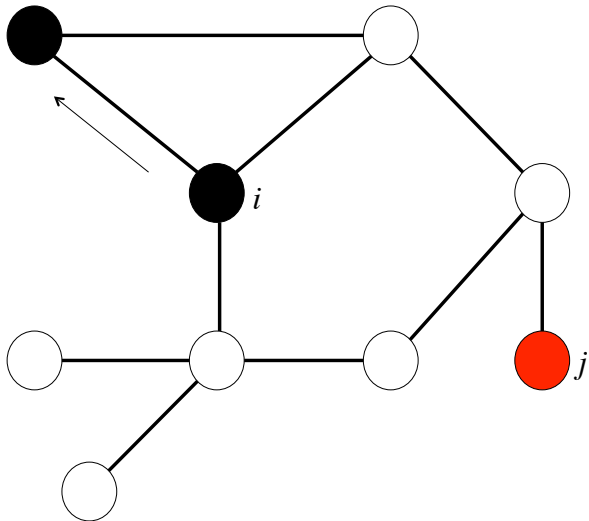


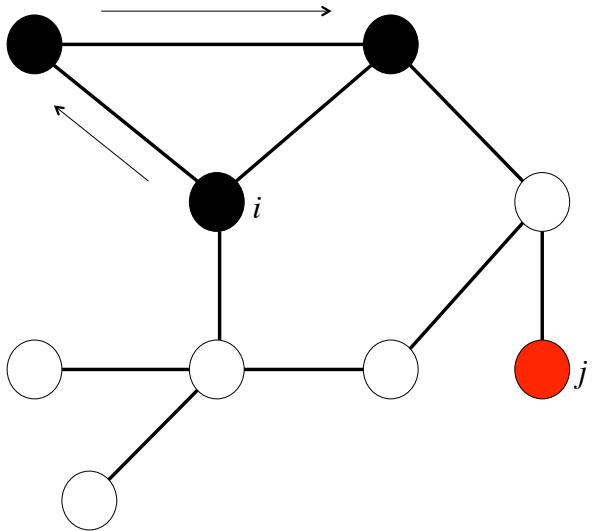


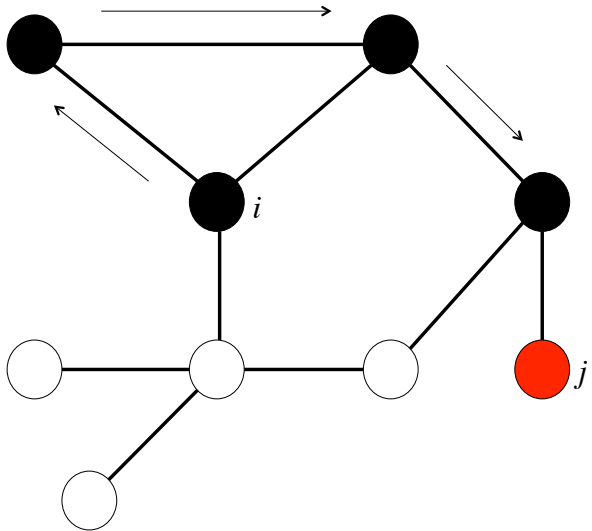


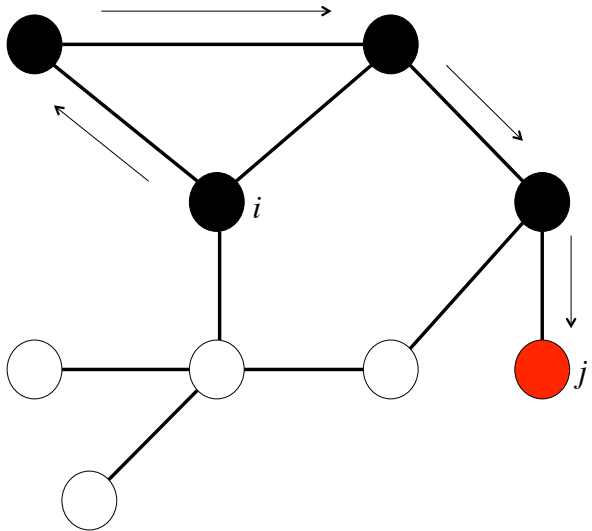












Degree sequence product

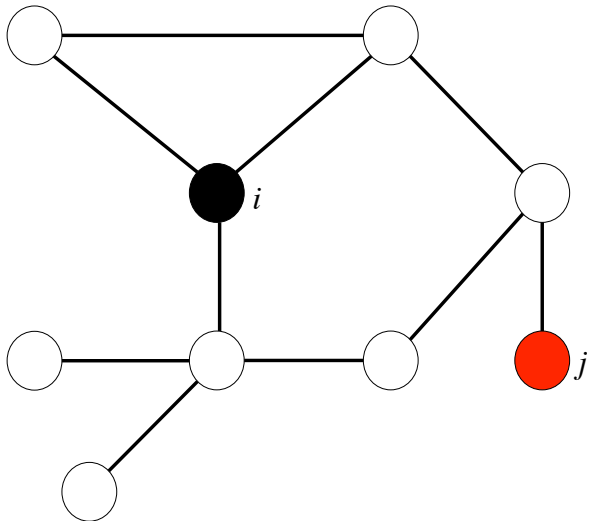
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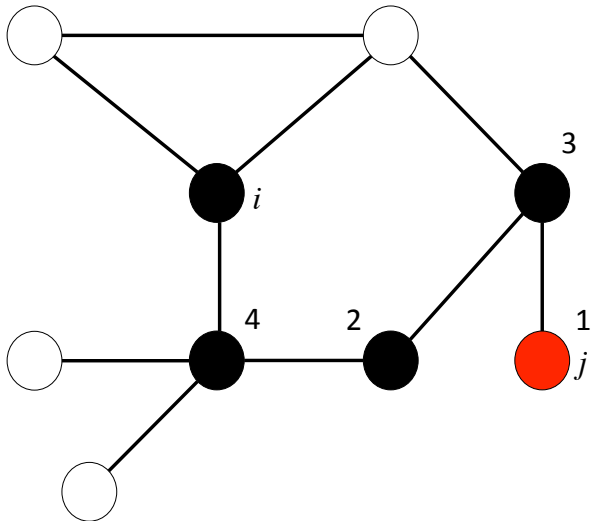
For a path P , a *degree sequence* along any path P is $(d_i(G))_{i \in P \setminus \{i_0\}}$.

Definition

A *degree sequence product* along P is:

$$\chi_P := \prod_{i \in P \setminus \{i_0\}} d_i(G)$$





Key proposition

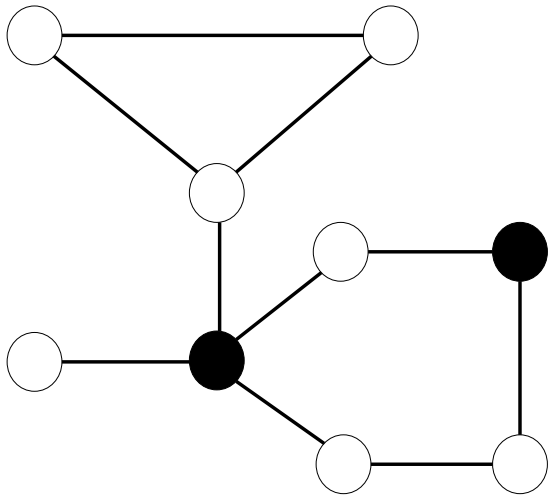
For any G and S_0 , let \mathcal{P}_{ji} be the set of all paths beginning at $j \in S_0$ and ending at $i \in V \setminus S_0$ and $\mathcal{P}_{ji}^* \subseteq \mathcal{P}_{ji}$ denote the subset of those paths that exclude any other node in S_0 .

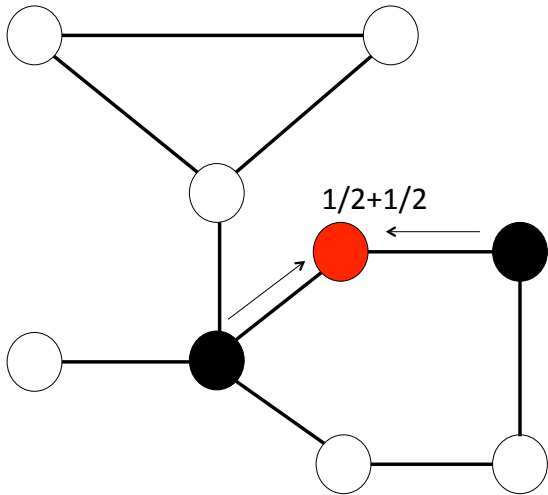
Proposition

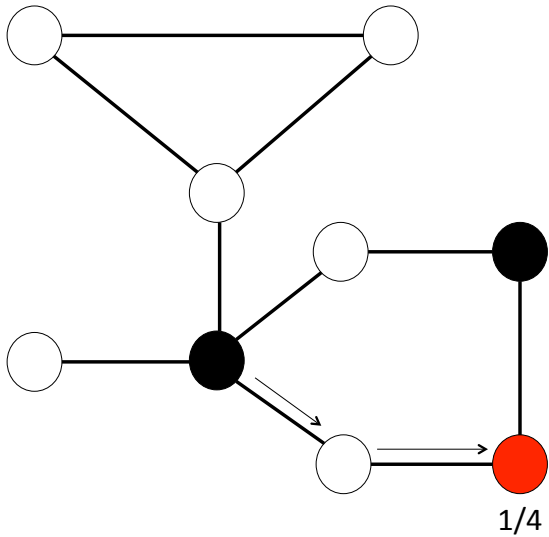
Suppose firm A is a monopolist. Given a graph G and seed S_0 , the probability that node $i \in V \setminus S_0$ adopts product a is:

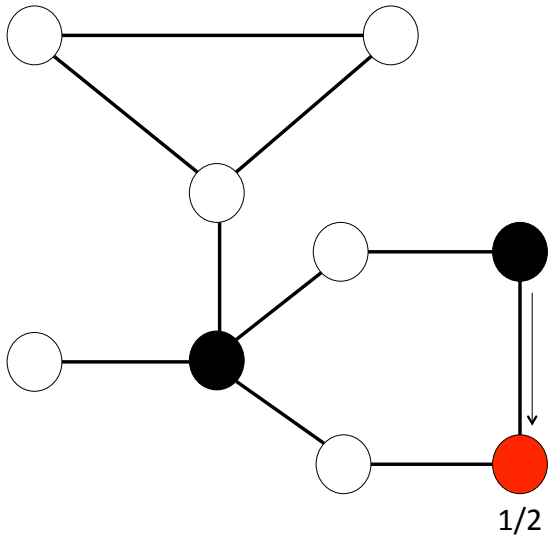
$$\mathbb{P}_i^A(G, S_0^A) = \sum_{j \in S_0} \sum_{P \in \mathcal{P}_{ji}^*} \frac{1}{\chi_P}$$

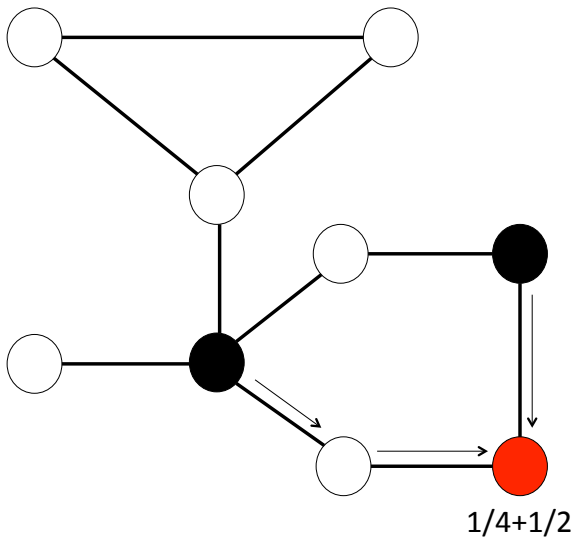
See Kempe et al. (2003); Chen et al. (2010).

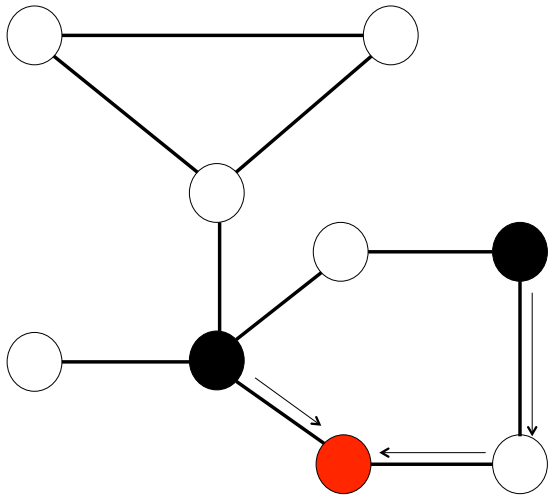




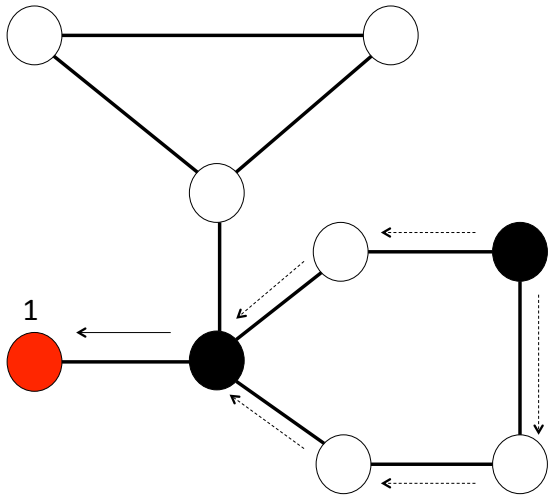


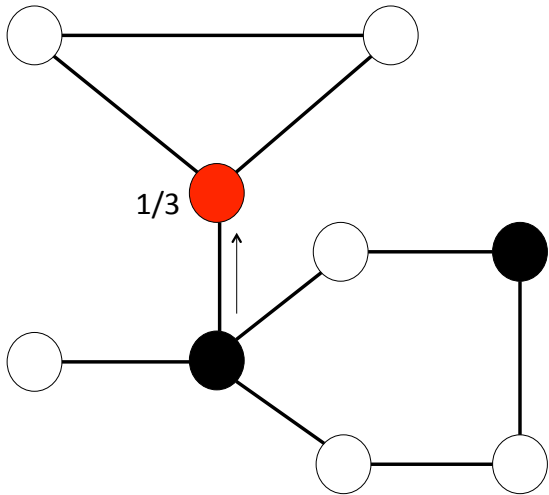


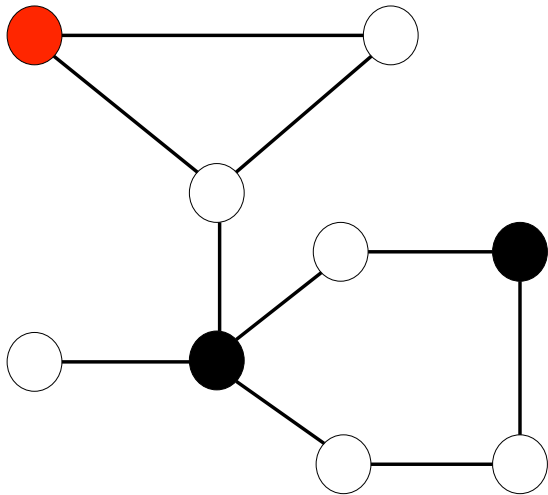


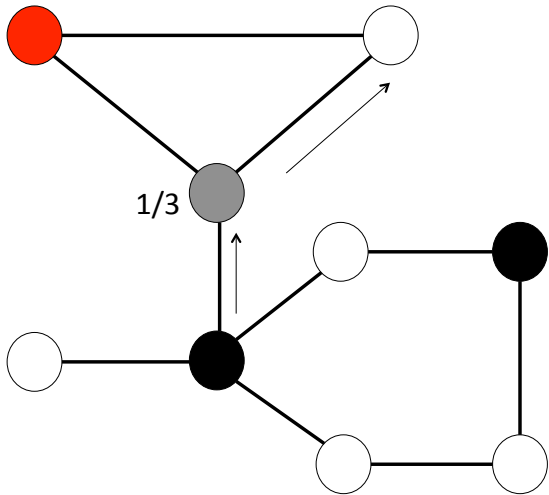


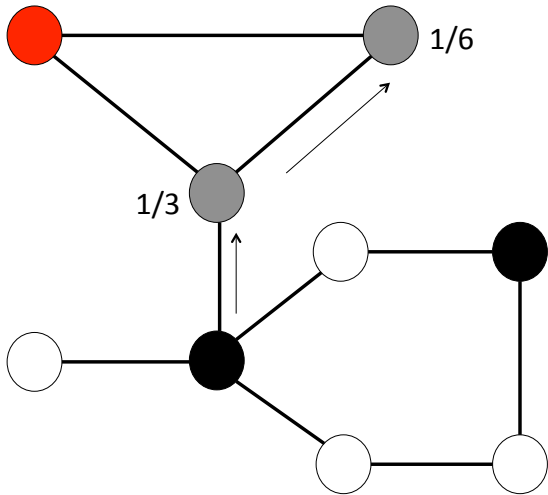
$$\frac{1}{2} + \frac{1}{4}$$

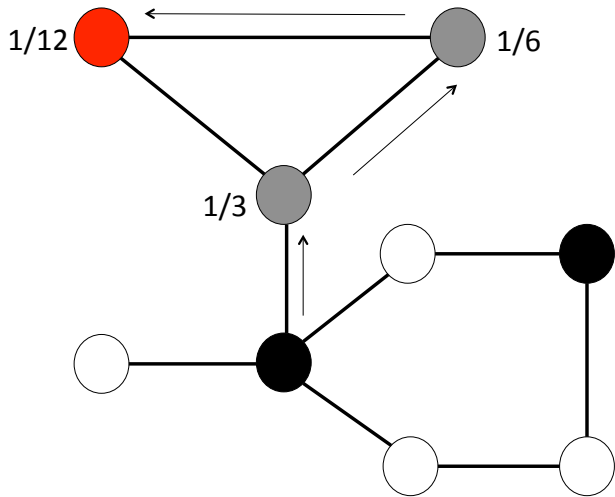


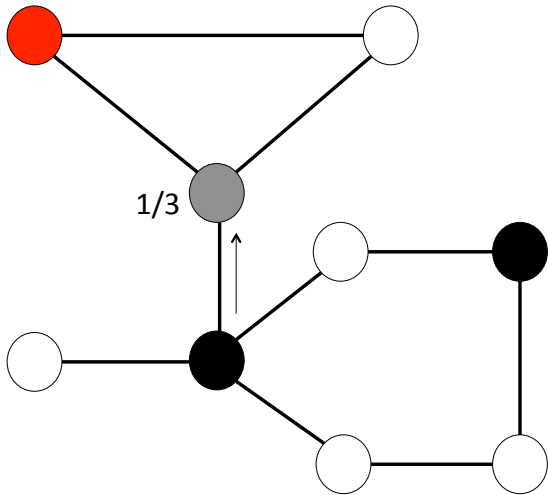


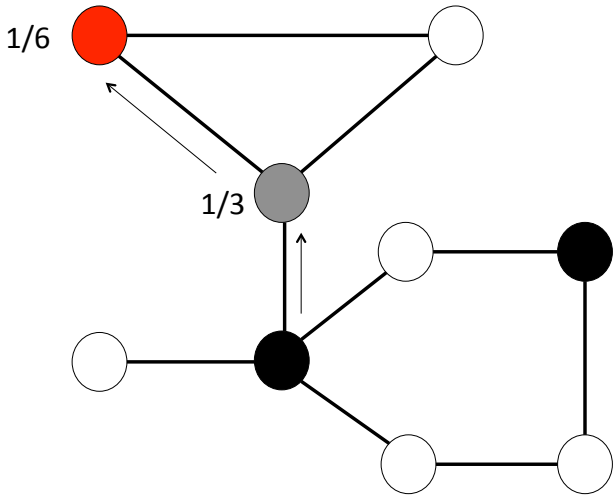


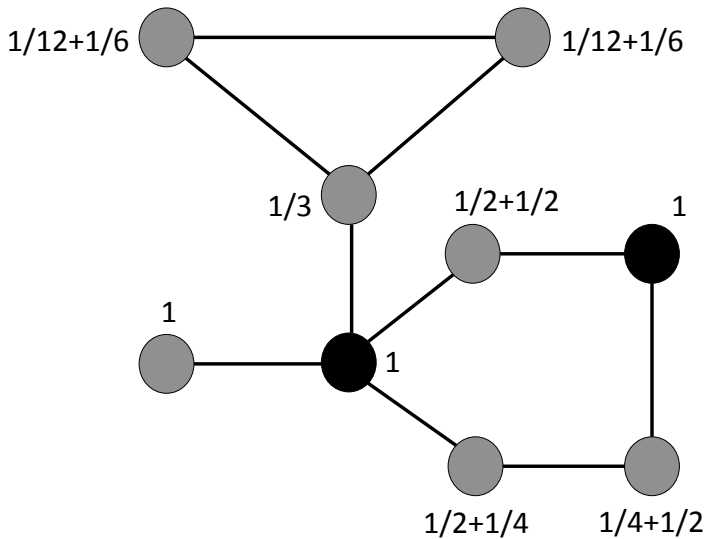












Cascade centrality

Definition

Cascade centrality of node i in graph G is the expected number of adopters of product a in that graph given i is the seed and firm A is a monopolist, namely

$$c_i(G) := \mathbb{E}[S^A(G, \{i\})] = 1 + \sum_{j \in V \setminus \{i\}} \mathbb{P}_j^A(G, \{i\}) = 1 + \sum_{j \in V \setminus \{i\}} \sum_{P \in \mathcal{P}_{ij}} \frac{1}{\chi^P}$$

Back to the duopoly...

Game: uniform thresholds

- Action space of firms A and B : $\Sigma := \Sigma_A \times \Sigma_B := V \times V$
- Action profile $\sigma := (\sigma_A, \sigma_B)$ is simply a pair of nodes.
- Payoff profile: $\pi := (\pi_A(\sigma), \pi_B(\sigma))$ is the expected number of adopter of products a and b .

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Game: uniform thresholds

- For $i \neq j$, let us denote $\Xi(i, j)$ as the set of all paths that begin at i and include (but do not necessarily end) at j .

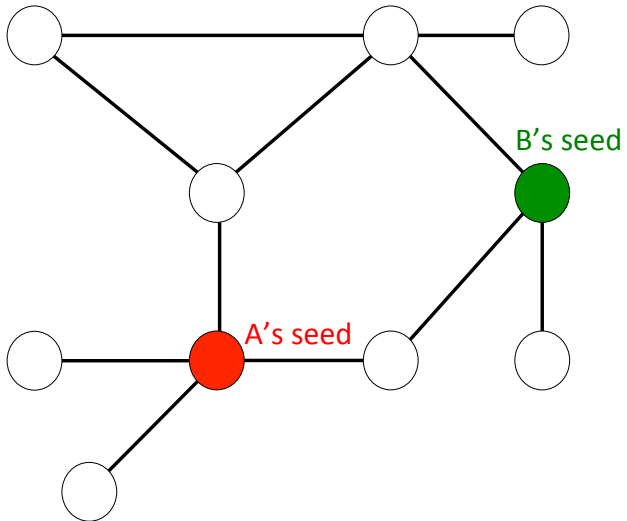
Proposition

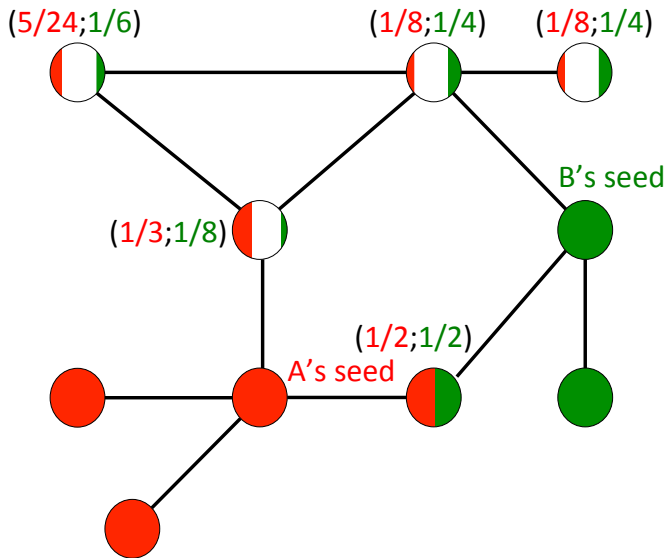
The expected number of adopters of product a (i.e. firm A 's payoff) is

$$\pi_A(\sigma_A, \sigma_B) = \begin{cases} \frac{C_{\sigma_A}}{2} & \text{if } \sigma_A = \sigma_B \\ C_{\sigma_A} - \epsilon(\sigma_A, \sigma_B) & \text{if } \sigma_A \neq \sigma_B \end{cases}$$

where

$$\epsilon(i, j) = \sum_{P \in \Xi(i, j)} \frac{1}{\chi^P}$$





- The game is defined as $\Gamma := (\Sigma, \pi)$.

Definition

A profile of actions $\sigma^* := (\sigma_A^*, \sigma_B^*) \in \Sigma$ is a pure-strategy Nash equilibrium if:

- $\pi_A(\sigma_A^*, \sigma_B^*) \geq \pi_A(\sigma_A, \sigma_B^*)$ for all actions $\sigma_A \in \Sigma_A$
- $\pi_B(\sigma_A^*, \sigma_B^*) \geq \pi_B(\sigma_A^*, \sigma_B)$ for all actions $\sigma_B \in \Sigma_B$

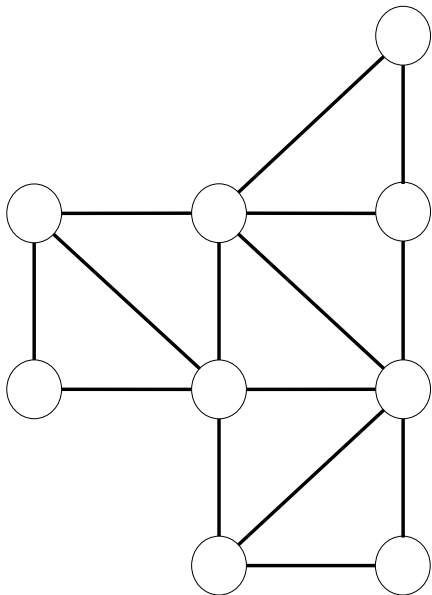
- Define Σ^* as the set of all pure-strategy Nash equilibria.

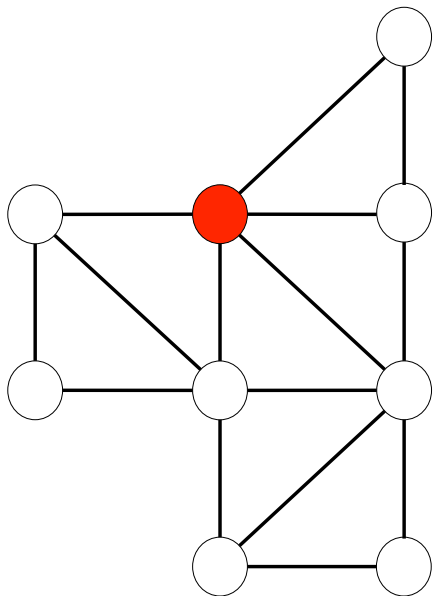
- The game is defined as $\Gamma := (\Sigma, \pi)$.

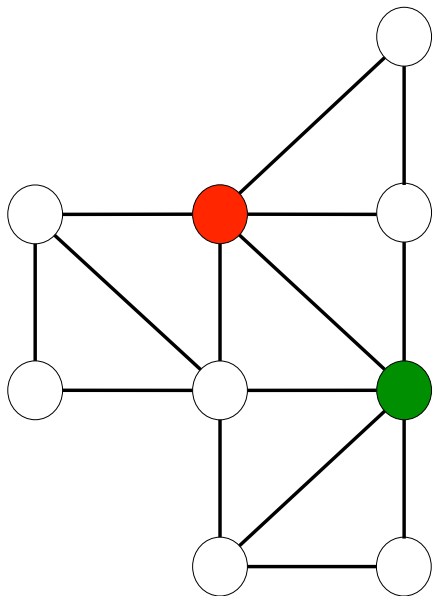
Definition

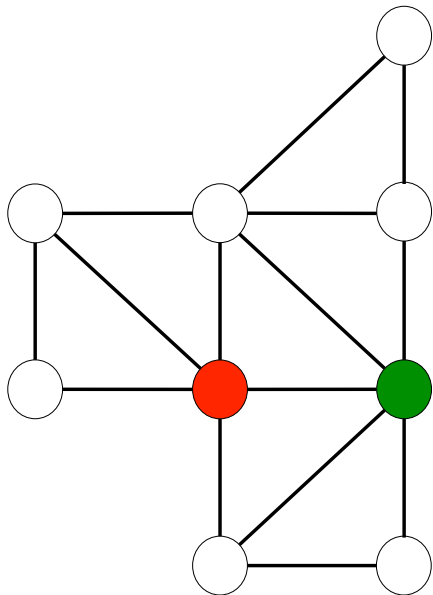
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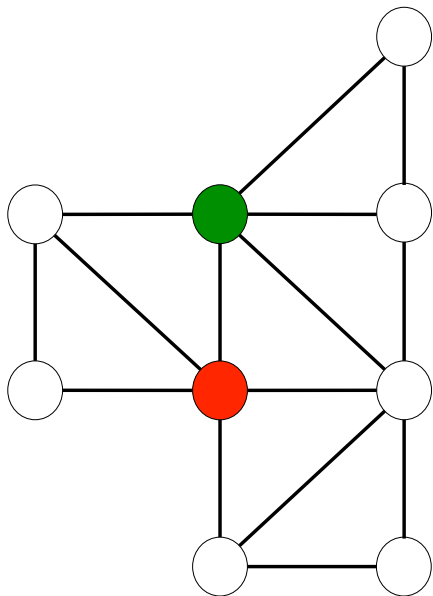
- $\pi_A(\sigma_A^*, \sigma_B^*) \geq \pi_A(\sigma_A, \sigma_B^*)$ for all actions $\sigma_A \in \Sigma_A$
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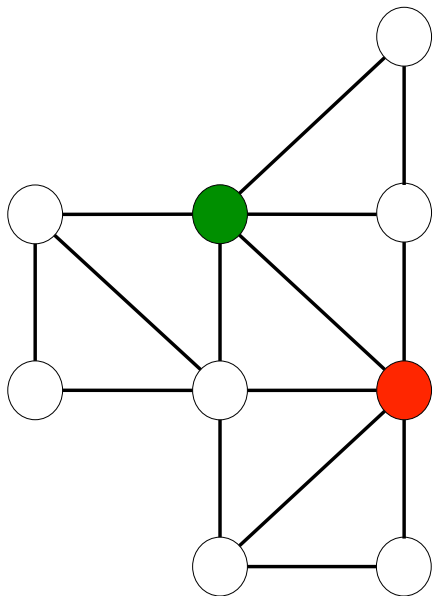












PSNE: existence characterization

Theorem

Consider a duopoly with unit budgets Γ . Then Γ admits at least one PSNE if and only if either:

1. There exists $i \in V$ such that, for any $j \in V \setminus \{i\}$:

- $$\frac{c_i}{c_j} \geq 2 - 2 \cdot \left(\frac{\epsilon(j, i)}{c_j} \right)$$

then there exists a $\sigma^* = (i, i)$ PSNE, or...

PSNE: existence characterization

Theorem

Consider a duopoly with unit budgets Γ . Then Γ admits at least one PSNE if and only if either Condition **1** is satisfied or

2. There exist $i, j \in V$ such that, $C_i \geq C_j$ and for any $k \in V \setminus \{i, j\}$:

- $\frac{C_i}{C_k} \geq 1 + \frac{\epsilon(i, j) - \epsilon(k, j)}{C_k}$
- $\frac{C_j}{C_k} \geq 1 + \frac{\epsilon(j, i) - \epsilon(k, i)}{C_k}$
- $\frac{1}{2} + \frac{\epsilon(i, j)}{C_j} \leq \frac{C_i}{C_j} \leq 2 - 2 \cdot \left(\frac{\epsilon(j, i)}{C_j} \right)$

in which case there exists a $\sigma^* = (i, j)$ (and $\sigma^* = (j, i)$ by symmetry) PSNE.

Budget multiplier

Definition

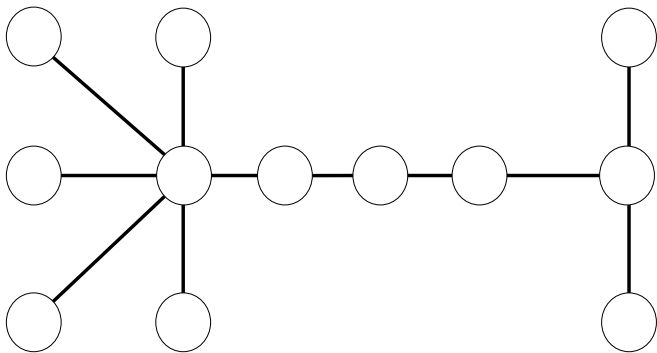
For arbitrary integer budgets \mathcal{B}_A and \mathcal{B}_B , the budget multiplier is defined as:

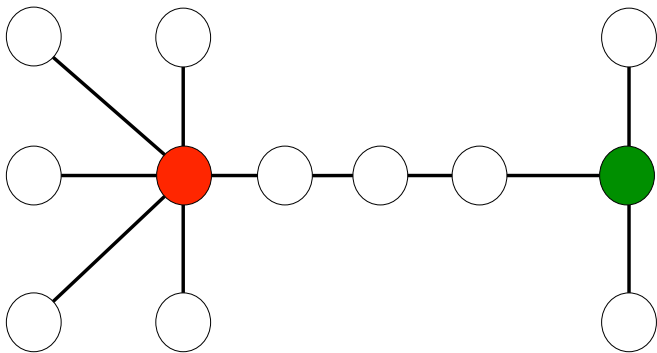
$$\text{BM}(\Gamma) := \max_{\sigma \in \Sigma^*} \frac{\pi_A(\sigma)/\pi_B(\sigma)}{\mathcal{B}_A/\mathcal{B}_B}$$

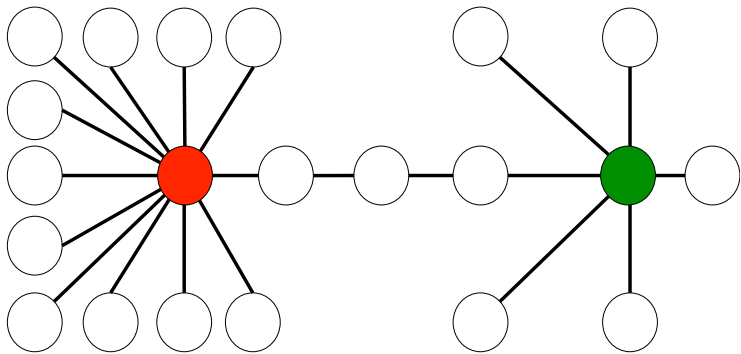
Theorem

For any Γ that admits at least one PSNE,

$$1 \leq \text{BM} < 2$$







Price of anarchy

Social planner's objective: $Y(\sigma) := \pi_A(\sigma) + \pi_B(\sigma)$ (i.e. firms' total payoffs).

Definition

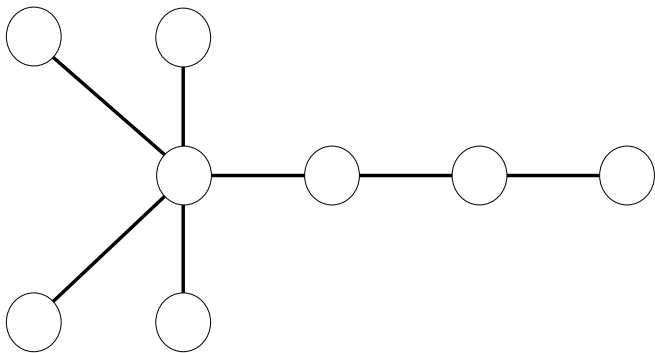
Price of Anarchy is defined as:

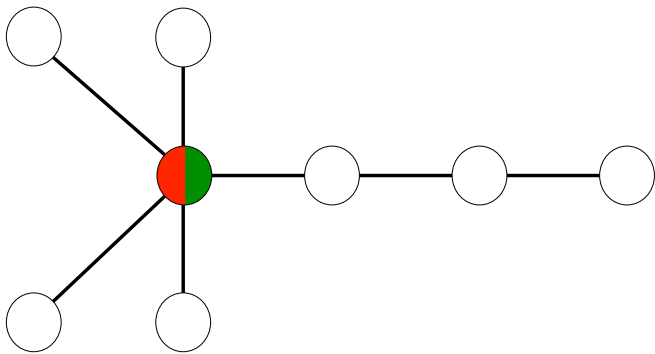
$$\text{PoA}(\Gamma) = \frac{\max_{\sigma \in \Sigma} Y(\sigma)}{\min_{\sigma \in \Sigma^*} Y(\sigma)}$$

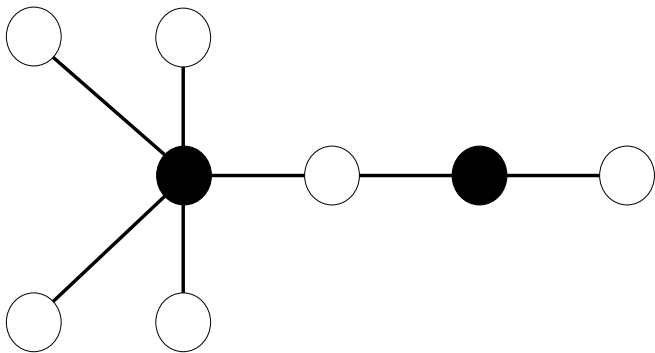
Theorem

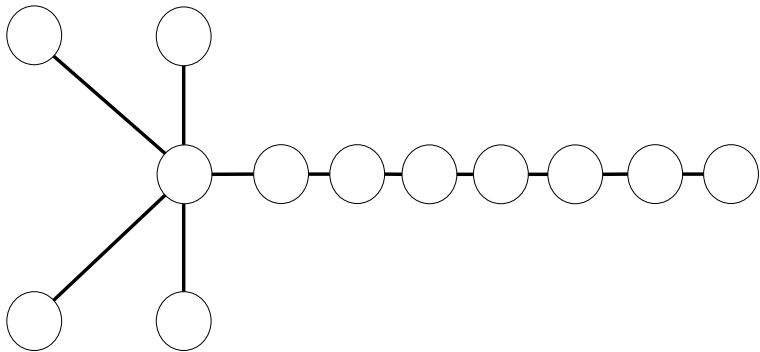
For any Γ that admits at least one PSNE,

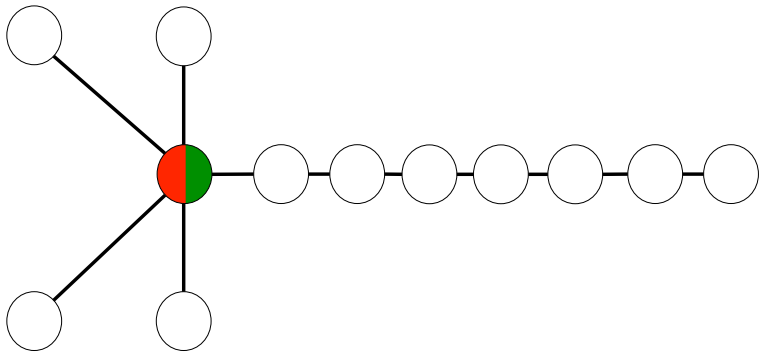
$$1 \leq \text{PoA}(\Gamma) < 1.5$$

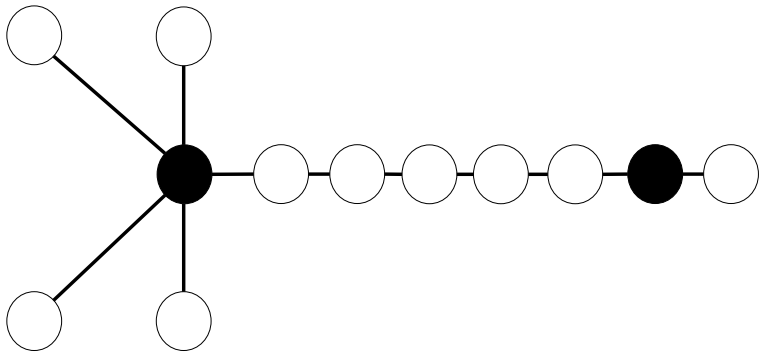












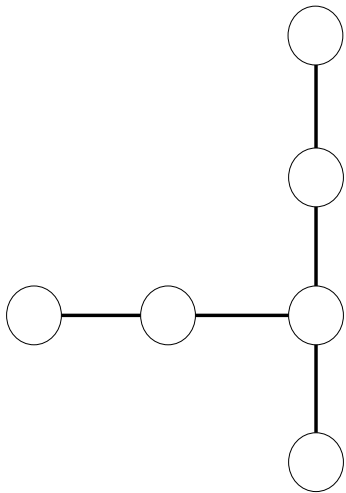
Trees

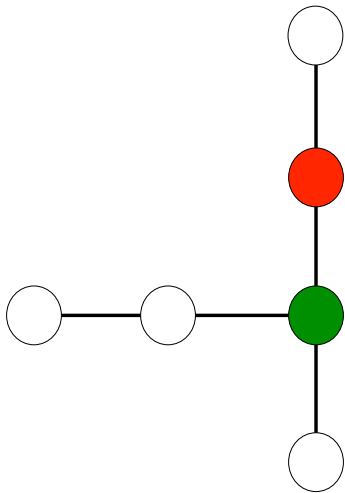
Proposition

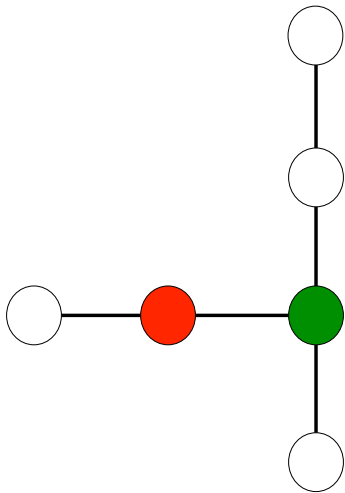
Suppose G is a tree. Then Γ admits at least one PSNE.

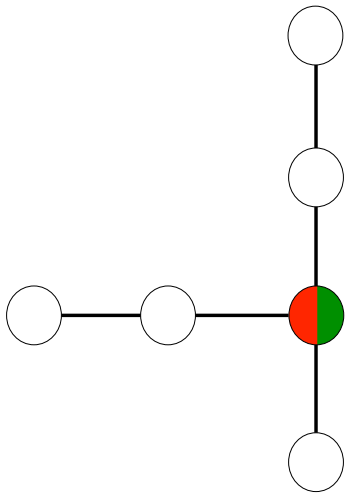
Trees

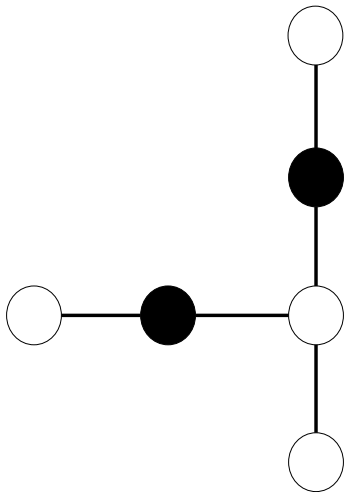
- We provide necessary and sufficient conditions only on the largest and second largest degree of the trees such that:
 - ▶ all PSNEs are efficient
 - ▶ no PSNEs are efficient
 - ▶ at least one PSNE is efficient
 - ▶ at least one PSNE is inefficient
 - ▶ there is at least one efficient and one inefficient PSNE











Conclusions

- Using a new notion of *cascade centrality*, we analyzed a tractable cascade process on general networks.
- We applied these insights to studying competitive diffusion.
- The competition model can be extended in a bunch of ways (different quality of products, sequential entry, multiple seeds).

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Main conclusion



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